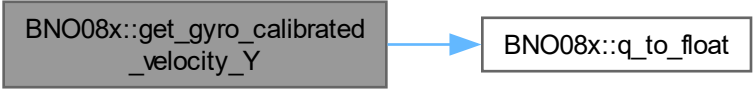


BNO08x::get_gyro_calibrated
_velocity_Y



```
graph LR; A[BNO08x::get_gyro_calibrated_velocity_Y] --> B[BNO08x::q_to_float]
```

BNO08x::q_to_float