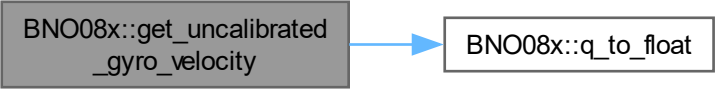


BNO08x::get\_uncalibrated  
\_gyro\_velocity



```
graph LR; A[BNO08x::get_uncalibrated_gyro_velocity] --> B[BNO08x::q_to_float]
```

BNO08x::q\_to\_float