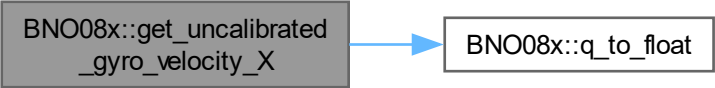


BNO08x::get_uncalibrated
_gyro_velocity_X



```
graph LR; A[BNO08x::get_uncalibrated_gyro_velocity_X] --> B[BNO08x::q_to_float]
```

BNO08x::q_to_float